Optimization of Surplus Reinsurance Treaty using the Conditional Tail Expectation

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Abstract
In this work, we propose a new optimization strategy for reinsurance using the genetic algorithms. This approach is to determine an optimal structure of a "surplus" reinsurance contract by finding the optimal cession rates through an optimization model which is based on the minimization of the Conditional Tail Expectation (CTE) risk measure under the constraint of technical benefit. This approach can be seen as a decision support tool that can be used by managers to minimize the actuarial risk and maximize the technical benefit in the insurance company.

Keywords: Augmented Lagrangian; Cession rate; Conditional Tail Expectation; Genetic algorithms; Reinsurance; Technical benefit.

1. Introduction
The search for an optimal reinsurance plan has always been an important part of actuarial mathematics. The main aim of an insurer is undoubtedly to maximize the expected technical benefit and to minimize risk measures under certain constraints. In this context, several models have been proposed to determine an optimal choice of reinsurance, the most popular of which is the one developed under the Mean-variance approach, which was first discussed in De Finetti’s [14] work. It should be noted that this approach is based on the criterion of minimizing the variance of technical benefit by keeping the mathematical expectation of technical benefit at a maximum level. De Finetti has studied this optimization problem in the case of a «quota share» reinsurance treaty. Several authors have developed the same strategy by treating the problem of mean-variance in different ways by applying several more generalized types of transformation than those used by De Finetti [14]. In this context, we have a set of papers dealing with the mean-variance approach and enriching actuarial literature, such as Arrow [5], Mossin [31], Smith [35], Ohlin [32], Raviv [33], Moffet [30], Blazenko [9] and Hess [23]…etc.
In the previous approaches, the authors applied a premium principle (pricing mode) based on mathematical expectation. Gajeck and Zagrodny [20] and Kaluszka [25] studied the same approach using the other bonus principles based on variance. This study results in an optimal reinsurance treaty that mixes the "quote share" and the "loss surplus" called "change-loss reinsurance". Walhin and Lampaert [38] applied the mean-variance approach to the form of proportional reinsurance of the "surplus" type. However, several criticisms were addressed to these models, such as the choice of variance as a measure of risk and the burden of computation. These criticisms give rise to a multitude of attempts to improve these models or to develop new models. In this light, many researchers have proposed new criteria for the optimal choice of reinsurance, there are, among others, Dickson and Waters [18], Aase [1], Krvavych [26], Deelstra and Plantin [15] who have chosen optimality by the minimization criterion of the probability of ruin while justifying this choice. However, several authors such as Ben Dbabis [7] have verified that the criterion of minimizing the probability of ruin alone does not lead to a rational decision for an optimal choice of reinsurance, because this criterion acts only on the risk (by minimizing the probability of ruin), but it does not act on the technical benefit, i.e., the insurer must not choose the optimal reinsurance treaty if it is not profitable.

For this reason, several researchers have introduced a new criterion for choosing optimal reinsurance based on the minimization of risk measures, such as Value-at-Risk (VaR) and Conditional Tail Expectation (CTE). This criterion was introduced by Cai and Tan [12] who disassembled the existence of explicit optimal retention in the case of "stop loss" treaty. The Cai and Tan [12] approach was then generalized by Tan and Chi [37] who used an auxiliary model to solve the optimal reinsurance treaty problem using the "CTE-minimization" model.

The various previous approaches that have started the literature on the problem of optimizing reinsurance, act either on the technical benefit (by maximizing it for a given risk), or on the risk (by minimizing it for a given technical benefit), but they do not act on both at the same time in a dynamic way. In fact, the use of the preceding optimization criteria alone does not generally lead to a rational decision, for the choice of optimal reinsurance. That is, minimizing risk does not always imply maximum technical benefit, and vice versa. So the insurer should not choose the optimal reinsurance treaty if it is not beneficial.

In this context, we have proposed practical solution for determining the optimal "surplus" reinsurance treaty through minimizing Conditional Tail Expectation risk measure under technical benefit constraints. In addition we have created an optimization procedure based on the Augmented Lagrangian method and the Genetic Algorithms to solve the optimization problem of this model.

The organization of this paper is as follows: the second section presents the Conditional Tail Expectation risk measure, then in the third section, we formulate our optimization problem, then in section 4 we propose the optimization procedure by the Augmented Lagrangian method and the Genetic Algorithms. Finally, in the last section, we illustrate our model of optimization by a sample application.
2. Conditional Tail Expectation (CTE)

**Definition 1.** The Conditional Tail Expectation (CTE) is a measure of risk corresponding to a random variable \( X \) at the probability level \( \theta \in [0,1] \), denoted by \( CTE_\theta(X) \) and defined by:

\[
CTE_\theta(X) = E \left[ X | X \geq VaR_\theta(X) \right].
\]

The expression (1) considers the tail of the distribution of \( X \) to the right of \( VaR_\theta(X) \).

**Proposition 1.** When \( X \) is continuous then we have the following equivalent expression:

\[
CTE_\theta(X) = \frac{1}{1-\theta} \int_{VaR_\theta(X)}^\infty x f_X(x) dx,
\]

with \( \frac{1}{1-\theta} \int_{VaR_\theta(X)}^\infty x f_X(x) dx \) being the Tail Value-at-Risk (TVaR\( _\theta(X) \)) which is the arithmetic mean of the (VaR) above \( \theta \).

**Proposition 2.** If \( X \) is continuous over its domain \( D_X \) then

That is:

\[
TVaR_\theta(X) = \frac{1}{1-\theta} \int_{VaR_\theta(X)}^\infty x f_X(x) dx,
\]

where \( f_X \) is the density function of the random variable \( X \).

**Proposition 3.** In general, the Conditional Tail Expectation is not a coherent measure. But it is coherent when the risks are continuous (TVaR and CTE are coincident).


3. Formulation of the optimization problem

Let a portfolio of claims expenses be represented by continuous and positive random variables \( X_1, \ldots, X_N \) with distribution functions \( F_{X_1}, \ldots, F_{X_N} \) and density functions \( f_{X_1}, \ldots, f_{X_N} \) and corresponding to the premiums \( P_1, \ldots, P_N \), with \( P = \sum_{i=1}^{N} P_i \).

The risks are considered independent and identically distributed, and independent of \( N \). With the sum of \( (X_i)_{i=1,\ldots,N} \) being zero, if \( N = 0 \).

Let \( X \) be a random variable denoting the total amount of claims, with the distribution function \( F_X \) and survival function \( S_X \), such that \( X = \sum_{i=1}^{N} X_i \).

The reinsurance contract is defined as follows:

\[
X = X^A + X^R,
\]

where \( X^A = \sum_{i=1}^{N} X_i^A \) and \( X^R = \sum_{i=1}^{N} X_i^R \).
The component $X^A$ is the insurer's claims burden and $X^R$ is the claims burden transferred to the reinsurer.

The reinsurer's charge shall in no way exceed the total claims burden, as it should not be negative, i.e. $0 \leq X^R \leq X$.

We consider the case of a form of proportional reinsurance of the "surplus" type. In this case, the insurer's shares and the reinsurer's shares are given respectively for each period by:

$$X^A_i = \min(X_i, a_i) + \frac{a_i}{m_i} \max(0, X_i - a_i), \text{ for } i \in [1,...,N]$$

and

$$X^R_i = \left(1 - \frac{a_i}{m_i}\right) \max(0, X_i - a_i), \text{ for } i \in [1,...,N].$$

knowing that $(m_i > 0)_{i=1,...,N}$ are the maximum amounts of a claim that the transferor wants to take to cover the risk, and $(a_i > 0)_{i=1,...,N}$ are the fixed values of the full retention that the ceding company retains its charge, for each risk, or $m_i \geq a_i, \forall i \in [1,...,N]$.

The cession rates $(\alpha_i)_{i=1,...,N}$ are given by the following formula:

$$\alpha_i = \frac{m_i - a_i}{m_i}, \quad \alpha_i \in [0,1], \text{ for } i \in [1,...,N].$$

For a detailed discussion of the (7) proposal the reader can consult Malinge [29].

Note that the insurer's primary objective is to find an optimal reinsurance and strategy allocation that will allow it to minimize risk and maximize its technical profit over a given period of time.

We propose a new strategy for the choice of optimal reinsurance which acts on the technical benefit (by maximizing it) and on the risk (by minimizing it), both at the same time in a dynamic way, with regard to the objective set by insurers, such as optimization with precision and ease of calculation using genetic algorithms.

We pose

$$a = (a_1,...,a_N), \quad m = (m_1,...,m_N) \quad \text{and} \quad X=(X_1,...,X_N).$$

To identify the risk we will use a coherent risk measure based on the Conditional Tail Expectation (CTE) of the technical benefit.

Let $E(B(X,a,m))$ and $CTE_\theta(B(X,a,m))$ are respectively the mathematical expectation and the Conditional Tail Expectation (CTE) of the technical benefit.
We construct the following optimization program:

\[
\begin{align*}
\min_{(a,m)} & \langle CTE_{m} \left( B(X,a,m) \right) \rangle \\
\text{s.t.} & \quad E \left( B(X,a,m) \right) = k, \quad \forall i \in [1,..,N], \\
& \quad a_i > 0, \\
& \quad a_i \leq m_i
\end{align*}
\]

such as \( k \) is the minimum earning expectation, set by the insurance company to be protected against bankruptcy.

This optimization problem consists in determining the pairs \( (a_i^*, m_i^*) \) which minimize both the risk (minimizing the Conditional Tail Expectation (CTE) of technical benefit) under the constraint of technical benefit which must be as equal the minimum earning expectation. This then allows the optimal cession to be determined from the following formula:

\[
\alpha_i^* = \frac{m_i^* - a_i^*}{m_i^*}, \quad \alpha_i \in [0,1], \quad \forall i \in [1,..,N].
\]

### Calculation of technical benefit:

Assume that the insurance company applies a pricing method \( \Pi \) that is based on the principle of mathematical expectation to cover the share of reinsurance, with a safety load \( \eta' = (\eta'_1,..,\eta'_N) \).

That is:

\[
\Pi(X_i^R) = (1 + \eta')E(X_i^R), \quad \text{for } i \in [1,..,N].
\]

Then, the premium charged by the insurer for the period \( i \) is given by:

\[
P_i^A (X_i,a_i,m_i) = E \left( \min \left( X_i, a_i \right) + \frac{a_i}{m_i} E \left( \left( X_i - a_i \right)_+ \right) \right), \quad \text{for } i \in [1,..,N].
\]

The premium charged by the reinsurer for the period \( i \) is given by:

\[
P_i^R (X_i,a_i,m_i) = (1 + \eta')E(X_i^R) = (1 + \eta') \left( 1 - \frac{a_i}{m_i} \right) E \left( \left( X_i - a_i \right)_+ \right), \quad \text{for } i \in [1,..,N] \]

It should be noted that the technical benefit (or technical result) is obtained by subtracting the net premiums collected during a period, the premium charged by the reinsurer and the expenses of the insurer.

The technical benefit \( B \) is given by:

\[
B(X,a,m) = \sum_{i=1}^{N} \left( P_i - P_i^R (X_i,a_i,m_i) - \left( \min \left( X_i, a_i \right) + \frac{a_i}{m_i} (X_i - a_i)_+ \right) \right)
\]
Then the mathematical expectation of the technical benefit is given by:

$$E(B(X,a,m)) = \sum_{i=1}^{N} \left[ P_i - P_i^R(X_i,a_i,m_i) - P_i^A(X_i,a_i,m_j) \right]$$

$$= \sum_{i=1}^{N} \left[ P_i \left(1 + \eta_i^* \right) \left( 1 - \frac{a_i}{m_j} \right) \left( X_i - a_i \right)_+ \right] - E \left[ \min(X_i,a_i) + \frac{a_i}{m_i} \left( X_i - a_i \right)_+ \right].$$

Therefore

$$E(B(X,a,m)) = P - \sum_{i=1}^{N} \left(1 + \eta_i^* \right) E \left[ \left( 1 - \frac{a_i}{m_i} \right) \left( X_i - a_i \right)_+ \right] - \sum_{i=1}^{N} E \left[ \min(X_i,a_i) + \frac{a_i}{m_i} \left( X_i - a_i \right)_+ \right]$$

(14)

- **Calculation of the Conditional Tail Expectation (CTE):**

The Conditional Tail Expectation (CTE) of the technical benefit is given by:

$$CTE_{\theta}(B(X,a,m)) = CTE_{\theta} \left[ \sum_{i=1}^{N} \left[ P_i - P_i^R(X_i,a_i,m_i) - \left( \min(X_i,a_i) + \frac{a_i}{m_i} \left( X_i - a_i \right)_+ \right) \right] \right]$$

$$= CTE_{\theta} \left[ \sum_{i=1}^{N} \left[ P_i \left(1 + \eta_i^* \right) \left( 1 - \frac{a_i}{m_i} \right) \left( X_i - a_i \right)_+ \right] - \left( \min(X_i,a_i) + \frac{a_i}{m_i} \left( X_i - a_i \right)_+ \right) \right]$$

(15)

According to the coherence properties of $CTE_{\theta}$ we have:

$$CTE_{\theta}(B(X,a,m)) = P - \sum_{i=1}^{N} \left(1 + \eta_i^* \right) E \left[ \left( 1 - \frac{a_i}{m_i} \right) \left( X_i - a_i \right)_+ \right] - CTE_{\theta} \left[ \sum_{i=1}^{N} \left[ \min(X_i,a_i) + \frac{a_i}{m_i} \left( X_i - a_i \right)_+ \right] \right]$$

(16)

For our optimization problem (8), we take the equality constraint on the technical benefit:

$$E(B(X,a,m)) = k.$$

Therefore

$$k = P - \sum_{i=1}^{N} \left(1 + \eta_i^* \right) E \left[ \left( 1 - \frac{a_i}{m_i} \right) \left( X_i - a_i \right)_+ \right] - E \left[ \sum_{i=1}^{N} \left[ \min(X_i,a_i) + \frac{a_i}{m_i} \left( X_i - a_i \right)_+ \right] \right],$$

which implies

$$\sum_{i=1}^{N} \left(1 + \eta_i^* \right) E \left[ \left( 1 - \frac{a_i}{m_i} \right) \left( X_i - a_i \right)_+ \right] = P - k - E \left[ \sum_{i=1}^{N} \left[ \min(X_i,a_i) + \frac{a_i}{m_i} \left( X_i - a_i \right)_+ \right] \right].$$

Replacing in (16), then the optimization program (8) is equivalent to minimizing the following objective function under certain domain constraints:

$$\begin{align*}
\min_{(X,a,m)} & \quad Z(X,a,m) = CTE_{\theta} \left[ \sum_{i=1}^{N} \left[ \min(X_i,a_i) + \frac{a_i}{m_i} \left( X_i - a_i \right)_+ \right] \right] - E \left[ \sum_{i=1}^{N} \left[ \min(X_i,a_i) + \frac{a_i}{m_i} \left( X_i - a_i \right)_+ \right] \right] \\
s.t. & \quad \quad a_i > 0, \forall i \in \{1, ..., N\} \\
& \quad \quad a_i \leq m_i, \forall i \in \{1, ..., N\}
\end{align*}$$

(17)
We pose
\[ h((X, a, m)) = \text{CTE}_0 \left( \sum_{i=1}^{N} \left[ \min(X_i, a_i) + \frac{a_i}{m_i} (X_i - a_i)_+ \right] \right) \]  
(18)
and
\[ g((X, a, m)) = E \left[ \sum_{i=1}^{N} \left[ \min(X_i, a_i) + \frac{a_i}{m_i} (X_i - a_i)_+ \right] \right] \]  
(19)
Then
\[ Z(X, a, m) = h((X, a, m)) - g((X, a, m)). \]
Let us now calculate the objective function \( Z(X, a, m) \):

**Calculation of \( g((X, a, m)) \):**

We have
\[ \min(X_i, a_i) = X_i - (X_i - a_i)_+, \quad \forall i \in [1, \ldots, N]. \]
Therefore
\[ g((X, a, m)) = E \left[ \sum_{i=1}^{N} \left[ 1 - \frac{a_i}{m_i} \right] \min(X_i, a_i) + \frac{a_i}{m_i} X_i \right] \]  
(20)
On the other hand, it is known that
\[ E \left( (X_i - a_i)_+ \right) = \int_{a_i}^{\infty} (x - a_i) f_{X_i}(x) dx = E(X_i) - \int_0^{a_i} S_{X_i}(x) dx \]
and
\[ E \left( \min(X_i, a_i) \right) = E(X_i) - E \left( (X_i - a_i)_+ \right) = \int_0^{a_i} S_{X_i}(x) dx \]
Therefore
\[ g((X, a, m)) = \sum_{i=1}^{N} \left[ 1 - \frac{a_i}{m_i} \right] \int_0^{a_i} S_{X_i}(x) dx + \frac{a_i}{m_i} E(X_i) \]  
(21)

**Calculation of \( h((X, a, m)) \):**

We pose \( Y_i = \min(X_i, a_i) \), \( \forall i \in [1, \ldots, N] \)

We have
\[ \text{CTE}_0(Y_i, a_i) = E \left[ Y_i | Y_i \geq \text{VaR}_0(Y_i, a_i) \right] \]
\[ = E \left[ \text{VaR}_0(Y_i, a_i) + Y_i - \text{VaR}_0(Y_i, a_i) \right] | Y_i \geq \text{VaR}_0(Y_i, a_i), \quad \forall i \in [1, \ldots, N]. \]
Therefore
\[ CTE_{\theta}(Y, a_i) = Var_{\theta}(Y, a_i) + \frac{\int_{VaR_{\theta}(Y, a_i)}^{\infty} S_{X_i}(x)dx}{Pr\{Y \geq Var_{\theta}(Y, a_i)\}}, \quad \forall i \in [1, \ldots, N] \] (22)

We also have
\[ Var_{\theta}(Y, a_i) = S_{X_i}^{-1}(1 - \theta), \quad \forall i \in [1, \ldots, N] \]
and
\[ \int_{VaR_{\theta}(Y, a_i)}^{\infty} S_{X_i}(x)dx = \int_{VaR_{\theta}(Y, a_i)}^{1} S_{X_i}(x)dx = \int_{S_{X_i}^{-1}(1 - \theta)}^{\infty} S_{X_i}(x)dx, \quad \forall i \in [1, \ldots, N]. \]

Furthermore
\[ Pr\{Y \geq Var_{\theta}(Y, a_i)\} = Pr\{Y = Var_{\theta}(Y, a_i)\} + S_{X_i}(VaR_{\theta}(Y, a_i)) \]
\[ = Pr\{Y = S_{X_i}(1 - \theta)\} + S_{X_i}(S_{X_i}^{-1}(1 - \theta)) = S_{X_i}(S_{X_i}^{-1}(1 - \theta)) = 1 - \theta, \quad \forall i \in [1, \ldots, N]. \]

We obtain then
\[ CTE_{\theta}(Y, a_i) = Var_{\theta}(Y, a_i) + \frac{1}{1 - \theta} \int_{S_{X_i}^{-1}(1 - \theta)}^{\infty} S_{X_i}(x)dx \]
\[ = S_{X_i}^{-1}(1 - \theta) + \frac{1}{1 - \theta} \int_{S_{X_i}^{-1}(1 - \theta)}^{\infty} S_{X_i}(x)dx, \quad \forall i \in [1, \ldots, N]. \] (23)

From where
\[ h((X, a, m)) = \sum_{i=1}^{N} \left[ \left( 1 - \frac{a_i}{m_i} \right) \left( S_{X_i}^{-1}(1 - \theta) + \frac{1}{1 - \theta} \int_{S_{X_i}^{-1}(1 - \theta)}^{\infty} S_{X_i}(x)dx \right) + \frac{a_i}{m_i} CTE_{\theta}(X_i) \right] \] (24)

On the other hand, according to proposition 1, we have:
\[ CTE_{\theta}(X_i) = \frac{1}{1 - \theta} \int_{VaR_{\theta}(X_i, a_i)}^{\infty} xf_{X_i}(x)dx = \frac{1}{1 - \theta} \int_{S_{X_i}^{-1}(1 - \theta)}^{\infty} xf_{X_i}(x)dx, \quad \forall i \in [1, \ldots, N] \] (25)

Therefore
\[ h((X, a, m)) = \sum_{i=1}^{N} \left[ \left( 1 - \frac{a_i}{m_i} \right) \left( S_{X_i}^{-1}(1 - \theta) + \frac{1}{1 - \theta} \int_{S_{X_i}^{-1}(1 - \theta)}^{\infty} S_{X_i}(x)dx \right) + \frac{a_i}{m_i} \int_{S_{X_i}^{-1}(1 - \theta)}^{\infty} xf_{X_i}(x)dx \right] \] (26)

Finally, replacing the expressions of (21) and (26) in (17), one obtains from the following the optimization problem:
\[ \max_{(a, m_{a_i}, m_i)} \left\{ Z(X, a, m) = \sum_{i=1}^{N} \left[ \left( 1 - \frac{a_i}{m_i} \right) \left( S_{X_i}^{-1}(1 - \theta) + \frac{1}{1 - \theta} \int_{S_{X_i}^{-1}(1 - \theta)}^{\infty} S_{X_i}(x)dx \right) + \frac{a_i}{m_i} \int_{S_{X_i}^{-1}(1 - \theta)}^{\infty} xf_{X_i}(x)dx \right] \right\} \]
\[ s.t \left\{ \begin{array}{l}
\sum_{i=1}^{N} \left[ \left( 1 - \frac{a_i}{m_i} \right) \int_{S_{X_i}(x)}^{\infty} + \frac{a_i}{m_i} E(X_i) \right] \\
\sum_{i=1}^{N} \left[ \left( 1 - \frac{a_i}{m_i} \right) \int_{S_{X_i}(x)}^{\infty} + \frac{a_i}{m_i} E(X_i) \right] \\
\left[ \frac{a_i}{m_i} \geq m_i, \quad \forall i \in [1, \ldots, N] \right]
\end{array} \right\} \] (27)
4. Optimization procedure by genetic algorithms

To solve the resulting optimization problem (27), we reformulate them as unconstrained optimization using the Augmented Lagrangian approach and run them with a genetic algorithm. This approach is very often used, since it allows finding a solution of sufficient rapidity without having to apply other sophisticated algorithms for constrained optimization. Augmented Lagrangian approach consists in replacing a constrained optimization problem by a series of problems without constraints by adding a penalty term to the objective function. In the Augmented Lagrangian, if the problem is subject to inequality constraints, it is sufficient to introduce a deviation variable to transform these constraints into equality constraints and to add a positivity constraint to the deviation variable.

**Note.** In the case of problems involving only equality constraints, we find a penalization of the classical Lagrangian.

Then the optimization problem is rewritten in the following equivalent form:

\[
\begin{align*}
\min_{\{a_i\}_{i=1}^N, \{\epsilon_i\}_{i=1}^N} & \left\{ Z(X,a,m) \right\} \\
\text{subject to} & \quad a_i > 0 \quad \forall i \in [1,..,N] \\
& \quad a_i \leq m_i 
\end{align*}
\]

\[
\Rightarrow \begin{align*}
\min_{\{a_i\}_{i=1}^N, \{\epsilon_i\}_{i=1}^N} & \left\{ Z(X,a,m) \right\} \\
\text{subject to} & \quad a_i - \epsilon_i = 0 \\
& \quad \epsilon_i \geq 0 \\
& \quad a_i - m_i + \epsilon_i' = 0 \\
& \quad \epsilon_i' \geq 0 \\
& \quad \forall i \in [1,..,N].
\end{align*}
\]

(28)

The Augmented Lagrangian function \( G(a,m,\rho,r,\epsilon,\epsilon') \) be defined as follows:

\[
G(a,m,\rho,r,\rho',r',\epsilon,\epsilon') = Z(X,a,m) - \sum_{i=1}^N \left[ \rho_i (a_i - \epsilon_i) + r_i (a_i - \epsilon_i)^2 \right] - \sum_{i=1}^N \left[ \rho'_i (a_i - m_i + \epsilon_i') + r'_i (a_i - m_i + \epsilon_i'^2) \right]
\]

(29)

with

- \( a = (a_1,..,a_N), \ m = (m_1,..,m_N) \) and \( x = (x_1,..,x_N) \);
- \( \rho = (\rho_1,..,\rho_N) \) and \( \rho' = (\rho'_1,..,\rho'_N) \): are the Lagrange multipliers and \( r = (r_1,..,r_N) \) and \( r' = (r'_1,..,r'_N) \) are the penalty parameters;
- \( \epsilon = (\epsilon_1,..,\epsilon_N) \) and \( \epsilon' = (\epsilon'_1,..,\epsilon'_N) \): are the deviation variables, such as \( \epsilon_i > 0, \forall i \in [1,..,N] \) and \( \epsilon_i' > 0, \forall i \in [1,..,N] \).

The principle of the method consists in resolving, iteratively, the problem without constraints which minimizes the Augmented Lagrangian function

\[
G(a,m,\rho,r,\rho',r',\epsilon,\epsilon').
\]

\( G \) should be minimized in relation to \((a,m)\), to \( \epsilon \) and to \( \epsilon' \).

The minimization of \( G(a,m,\rho,r,\rho',r',\epsilon,\epsilon') \) with respect to \( \epsilon \) and to \( \epsilon' \), for \((a,m)\) fixed, can be carried out analytically, leading to \( \epsilon \) and to \( \epsilon' \):
We have more
\[
\frac{\partial G}{\partial e_i} = \rho_i + 2r_i(a_i - e_i) = 0 \quad \forall i \in [1,\ldots,N],
\]
\[
\frac{\partial G}{\partial e'_i} = -\rho'_i - 2r'_i(a_i - m_i + e'_i) = 0.
\]
Thus, the minimum is met for
\[
\begin{align*}
e^*_i &= a_i + \frac{\rho_i}{2r_i}, \\
e'^*_i &= m_i - a_i - \frac{\rho'_i}{2r'_i}, \\
&\forall i \in [1,\ldots,N].
\end{align*}
\]
We thus resort to a problem dependent only on variables \((a,m,\rho,r,\rho',r')\):
\[
G(a,m,\rho,r,\rho',r') = Z(X,a,m) + \sum_{i=1}^{N} \left( \frac{\rho_i^2}{4r_i^2} + \frac{\rho'^2}{4r'_i} \right) \tag{30}
\]
There are also a number of optimization codes based on the Augmented Lagrangian approach, for example, Birgin and al [8], Andreani and al [3].

However, the approach of Lagrangian Augmented alone does not generally allow to optimize especially in the cases of the most mathematically complex problems which are difficult to solve algebraically.

Therefore, we have developed a dynamic Algorithm in this work that combines Augmented Lagrangian and Genetic Algorithms.

\begin{algorithm}
1. Create Augmented Lagrangian function \(G\);
2. Initialize the multiplier and the penalty factor \((\rho_0,\rho'_0,r'_0)\);
3. Initialize the \((a_0,m_0)\);
4. \(j = 0\);
5. As long as the stopping criterion is not verified, i.e. \(\nabla G_j(a_j,m_j,\rho_j,r_j,\rho'_j,r'_j)\) is not negligible:
   - \(j \leftarrow j + 1\);
   - Create the objective function \(G_j(a_j,m_j,\rho_j,r_j,\rho'_j,r'_j)\);
6. Run Genetic Algorithms for the objective function \(G_j(a_j,m_j,\rho_j,r_j,\rho'_j,r'_j)\);
7. Update the optimal values of \((a_j,m_j,\rho_j,r_j,\rho'_j,r'_j)\) (after running the GA-optimization program);
8. Return the result \((a^*,m^*)\).
\end{algorithm}
5. Application

Suppose loss amounts \((X_i)_{i=1,...,N}\) follow the Uniform Law \(U[0,2]\) of the following characteristics:

\[
E(X_i) = 1; \quad \text{Var}(X_i) = \frac{1}{3}; \quad f_{X_i}(x) = \frac{1}{2}, \quad 0 \leq x \leq 2; \quad F_{X_i}(x) = \frac{x}{2}, \quad 0 \leq x < 2; \quad \text{and} \quad S_{X_i}(x) = 1 - F_{X_i}(x) = 1 - \frac{x}{2}, \quad 0 \leq x < 2. \forall i \in [1,...,N].
\]

Let \(\theta = 0.05\) the probability level.

We consider a horizon of 9 years \((N = 9)\);

We have

- \(S_{X_i}^1(1 - \theta) = 2(1 - (1 - \theta)) = 2\theta\);
- \(\int_{S_{X_i}^1(1 - \theta)}^2 x f_{X_i}(x)dx = \int_{2\theta}^2 \frac{x}{2} dx = 1 - \theta^2\);
- \(\alpha^\alpha \int_0^a S_X(x)dx = \int_0^a \left(1 - \frac{x}{2}\right) dx = a - \frac{a^2}{4}\);
- \(\int_{S_{X_i}^1(1 - \theta)}^a S_{X_i}(x)dx = \int_{2\theta}^a \left(1 - \frac{x}{2}\right) dx = a - \frac{a^2}{4} - (2\theta - \theta^2)\).

After running the GA-optimization program developed by the recent GA solver of Matlab software, we got the following result of the optimization problem (30):

\[
\begin{array}{ccc}
\alpha_i^* & m_i^* & \alpha_i^* = \frac{m_i^* - \alpha_i^*}{m_i^*} \\
0.08 & 0.105 & 0.236 \\
7.523 & 66.575 & 0.887 \\
11.053 & 98.688 & 0.888 \\
12.909 & 248.250 & 0.948 \\
10.276 & 71.860 & 0.857 \\
10.747 & 45.155 & 0.762 \\
7.478 & 22.190 & 0.663 \\
8.968 & 70.614 & 0.873 \\
4.355 & 29.626 & 0.853 \\
\end{array}
\]

5. Conclusion

In this paper, we proposed a reinsurance optimization model, based on the minimization of the Conditional Tail Expectation (CTE) risk measure under the constraint of technical benefit. We have developed an optimization procedure based on the Augmented Lagrangian method and the Genetic Algorithms to solve the optimization problem of this model.
This method has shown its effectiveness in terms of the results obtained compared with those in the literature, in terms of its simplicity (effective for optimization problems that are difficult to solve algebraically), or at the level of its precision (improved optimization) which acts on the measure of risk and on the technical benefit, both at the same time with regard to achieving the goal of the insurance company such as maximizing technical benefit and minimizing risk.

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